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#### PS21964-A



#### INTEGRATED POWER FUNCTIONS

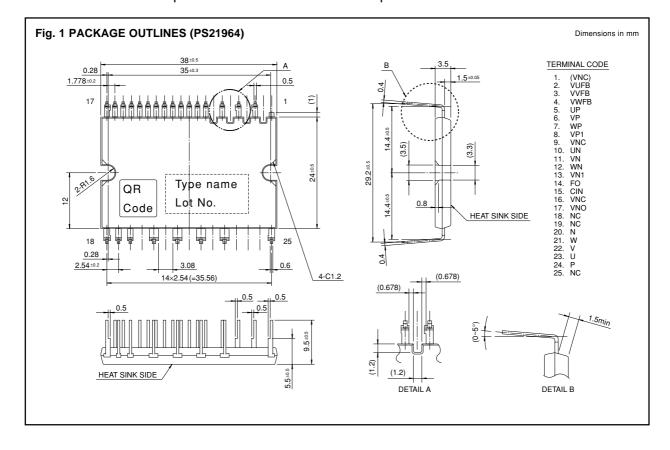
600V/15A low-loss  $5^{th}$  generation IGBT inverter bridge for three phase DC-to-AC power conversion

#### INTEGRATED DRIVE, PROTECTION AND SYSTEM CONTROL FUNCTIONS

- For upper-leg IGBTs: Drive circuit, High voltage isolated high-speed level shifting, Control supply under-voltage (UV) protection.
- For lower-leg IGBTs: Drive circuit, Control supply under-voltage protection (UV), Short circuit protection (SC).
- Fault signaling: Corresponding to an SC fault (Lower-leg IGBT) or a UV fault (Lower-side supply).
- Input interface: 3V, 5V line (High Active).

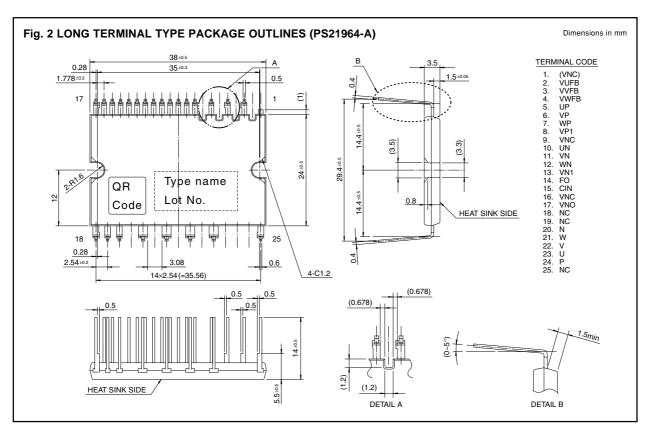
### **APPLICATION**

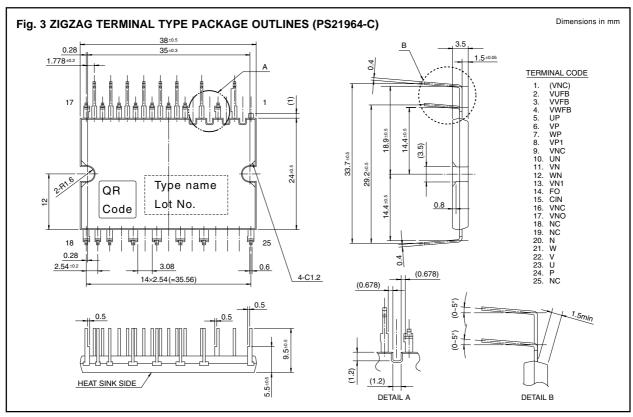
AC100V~200V three-phase inverter drive for small power motor control.



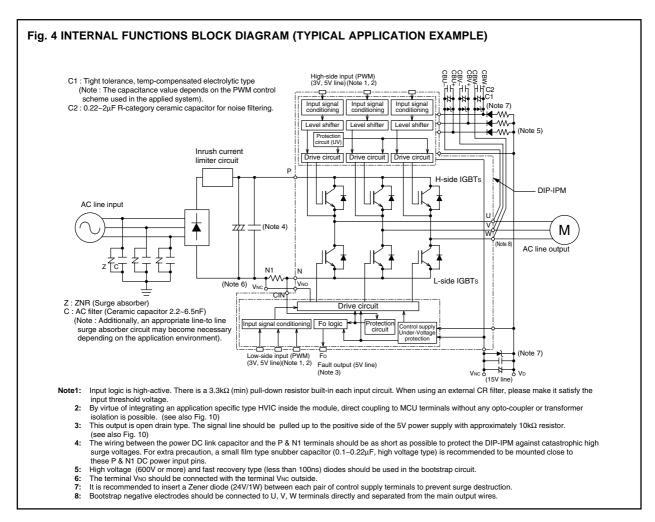


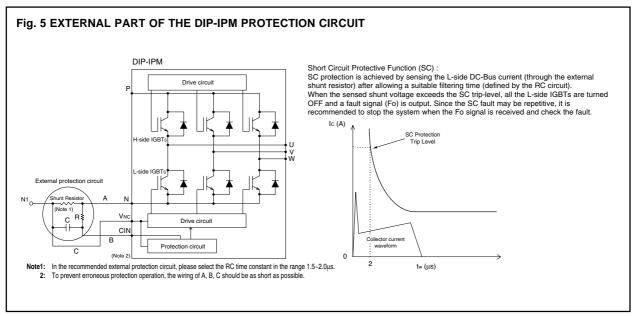
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#### **MAXIMUM RATINGS** ( $T_j = 25^{\circ}C$ , unless otherwise noted)

#### **INVERTER PART**

Symbol	Parameter	Condition	Ratings	Unit
Vcc	Supply voltage	Applied between P-N	450	V
VCC(surge)	Supply voltage (surge)	Applied between P-N	500	V
VCES	Collector-emitter voltage		600	V
±lc	Each IGBT collector current	Tc = 25°C	15	Α
±ICP	Each IGBT collector current (peak)	Tc = 25°C, less than 1ms	30	Α
Pc	Collector dissipation	Tc = 25°C, per 1 chip	33.3	W
Tj	Junction temperature	(Note 1)	-20~+125	°C

Note 1: The maximum junction temperature rating of the power chips integrated within the DIP-IPM is  $150^{\circ}$ C (@ Tc  $\leq 100^{\circ}$ C). However, to ensure safe operation of the DIP-IPM, the average junction temperature should be limited to  $T_{j(ave)} \leq 125^{\circ}$ C (@ Tc  $\leq 100^{\circ}$ C).

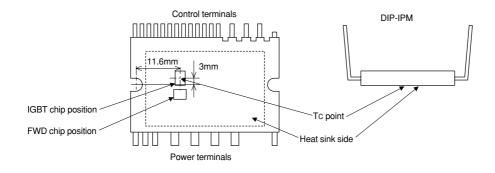
#### **CONTROL (PROTECTION) PART**

Symbol	Parameter	Condition	Ratings	Unit
VD	Control supply voltage	Applied between VP1-VNC, VN1-VNC	20	V
VDB	Control supply voltage	Applied between Vufb-U, Vvfb-V, Vwfb-W	20	V
VIN	Input voltage	Applied between UP, VP, WP, UN, VN, WN-VNC	-0.5~VD+0.5	V
VFO	Fault output supply voltage	Applied between Fo-VNC	-0.5~VD+0.5	V
IFO	Fault output current	Sink current at Fo terminal	1	mA
Vsc	Current sensing input voltage	Applied between CIN-VNC	-0.5~VD+0.5	V

#### **TOTAL SYSTEM**

Symbol	Parameter	Condition	Ratings	Unit
VCC(PROT)	Self protection supply voltage limit (short circuit protection capability)	$VD = 13.5$ ~16.5V, Inverter part $T_j = 125$ °C, non-repetitive, less than 2μs	400	V
Tc	Module case operation temperature	(Note 2)	<b>−</b> 20~+100	°C
Tstg	Storage temperature		<b>−</b> 40~+125	°C
Viso	Isolation voltage	60Hz, Sinusoidal, AC 1 minutes, All connected pins to heat-sink plate	1500	Vrms

Note 2: To measurement point





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#### THERMAL RESISTANCE

Symbol Pa	Davamatav	O and distant		Limits		
	Parameter	Condition	Min.	Тур.	Max.	Unit
Rth(j-c)Q	Junction to case thermal	Inverter IGBT part (per 1/6 module)		_	3.0	°C/W
Rth(j-c)F	resistance (Note 3)	Inverter FWD part (per 1/6 module)		_	3.9	°C/W

Note 3: Grease with good thermal conductivity should be applied evenly with about +100µm~+200µm on the contacting surface of DIP-IPM

and heat-sink. The contacting strate of DII-IIM case and heat sink (Rth(c-f)) is determined by the thickness and the thermal conductivity of the applied grease. For reference, Rth(c-f) (per 1/6 module) is about  $0.3^{\circ}$ C/W when the grease thickness is  $20\mu m$  and the thermal conductivity is  $1.0W/m \cdot k$ .

## **ELECTRICAL CHARACTERISTICS** (Tj = 25°C, unless otherwise noted)

#### **INVERTER PART**

Cumple of	Davamatav	Condition		Limits			Unit	
Symbol	Parameter		Condition		Тур.	Max.	Unit	
VCE(sat)	Collector-emitter saturation	VD = VDB = 15V	Ic = 15A, Tj = 25°C	_	1.70	2.20		
VCE(Sat)	voltage	VIN = 5V	IC = 15A, Tj = 125°C	_	1.80	2.30	V	
VEC	FWD forward voltage	$T_j = 25^{\circ}C$ , $-IC = 15A$ , $V_iN = 0V$		_	1.70	2.20	V	
ton		VCC = 300V, VD = VDB = 15V IC = 15A, Tj = 125°C, VIN = $0 \leftrightarrow 5V$		0.70	1.30	1.90	μs	
trr				_	0.30	_	μs	
tc(on)	Switching times			_	0.50	0.75	μs	
toff		Inductive load (upper-lov	Inductive load (upper-lower arm)		1.60	2.20	μs	
tc(off)				_	0.50	0.80	μs	
ICES	Collector-emitter cut-off	Vce = Vces	Tj = 25°C	_	_	1	mA	
1020	current	VCE = VCES	Tj = 125°C	_	_	10	IIIA	

#### **CONTROL (PROTECTION) PART**

Cumple al	Davamatav		0	ndition		Limits		Unit
Symbol	Parameter		Col	ndition	Min.	Тур.	Max.	Offit
		VD = VDB = 15V Total of VP1-VNC, VN1-V		of VP1-VNC, VN1-VNC	_	_	2.80	mA
ID	Circuit current	VIN = 5V	VUFB-	U, Vvfb-V, Vwfb-W	_	_	0.55	mA
ם ו	Circuit current	VD = VDB = 15V	Total of	of VP1-VNC, VN1-VNC	_	_	2.80	mA
		VIN = 0V	VUFB-	U, VVFB-V, VWFB-W	_	_	0.55	mA
VFOH	Fo output voltage	Vsc = 0V, Fo terminal pull-up to 5V by 10kΩ			4.9	_	_	V
VFOL	FO output voltage	VSC = 1V, IFO = 1mA			_	_	0.95	V
VSC(ref)	Short circuit trip level	$T_j = 25^{\circ}C, V_D = 15V$ (Note 4)			0.43	0.48	0.53	V
lin	Input current	VIN = 5V		0.70	1.00	1.50	mA	
UVDBt		Trip level	Trip level	10.0	_	12.0	V	
UVDBr	Control supply under-voltage	   T <sub>i</sub> ≤ 125°C		Reset level	10.5	_	12.5	V
UVDt	protection	1] ≤ 125 C		Trip level	10.3	_	12.5	V
UVDr				Reset level	10.8	_	13.0	V
tFO	Fault output pulse width			(Note 5)	20	_	_	μs
Vth(on)	ON threshold voltage					2.1	2.6	V
Vth(off)	OFF threshold voltage	Applied between LD VD MD LIN VA MA VA		0.8	1.3	_	V	
Vth(hys)	ON/OFF threshold hysteresis voltage	Applied between UP, VP, WP, UN, VN, WN-VNC			0.35	0.65	_	٧

Note 4: Short circuit protection is functioning only for the lower-arms. Please select the external shunt resistance such that the SC trip-level is less than 1.7 times of the current rating.

5: Fault signal is asserted corresponding to a short circuit or lower side control supply under-voltage failure.



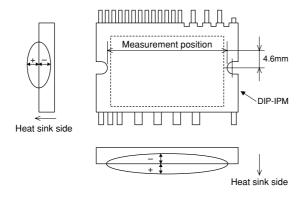
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#### **MECHANICAL CHARACTERISTICS AND RATINGS**

Doromotor	Con	Limits			Unit	
Parameter	Con	dition	Min.	Тур.	Max.	Unit
Mounting torque	Mounting screw : M3 (Note 6) Recommended : 0.69 N·m		0.59	_	0.78	N·m
Weight			_	10	_	g
Heat-sink flatness (Note 7)		<del>-</del> 50	_	100	μm	

Note 6: Plain washers (ISO 7089~7094) are recommended.

Note 7: Flatness measurement position



#### **RECOMMENDED OPERATION CONDITIONS**

Cumphal	bol Parameter Condition				Limits		Unit
Symbol Parameter		Condition	Condition		Тур.	Max.	Offic
Vcc	Supply voltage	Applied between P-N			300	400	V
VD	Control supply voltage	Applied between VP1-VNC, VN1-VNC		13.5	15.0	16.5	V
VDB	Control supply voltage	Applied between VUFB-U, VVFB-V, VWFB-	W	13.0	15.0	18.5	V
$\Delta V$ D, $\Delta V$ DB	Control supply variation				_	1	V/µs
tdead	Arm shoot-through blocking time	For each input signal, Tc ≤ 100°C		1.5	_	_	μs
l.		VCC = 300V, VD = VDB = 15V,	fPWM = 5kHz	_	_	7.5	
lo	Output r.m.s. current	$ \begin{array}{l} P.F = 0.8, \mbox{ sinusoidal PWM,} \\ T_{j} \leq 125^{\circ}\mbox{C, } T\mbox{C} \leq 100^{\circ}\mbox{C} \end{array} \tag{Note 8} $	fPWM = 15kHz	_	_	4.5	Arms
PWIN(on)	Allowable minimum input		0.5	_	_		
PWIN(off)	pulse width		0.5	_	_	μs	
VNC	VNC voltage variation	Between VNC-N (including surge)		-5.0	_	5.0	V

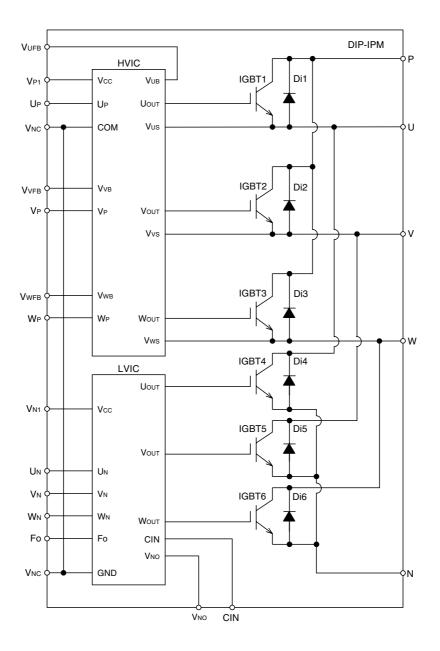
Note 8: The allowable r.m.s. current value depends on the actual application conditions.



<sup>9:</sup> IPM might not make response if the input signal pulse width is less than the recommended minimum value.

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Fig. 6 THE DIP-IPM INTERNAL CIRCUIT



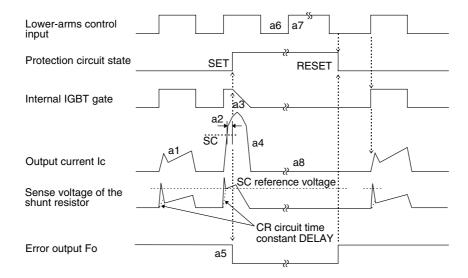


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#### Fig. 7 TIMING CHART OF THE DIP-IPM PROTECTIVE FUNCTIONS

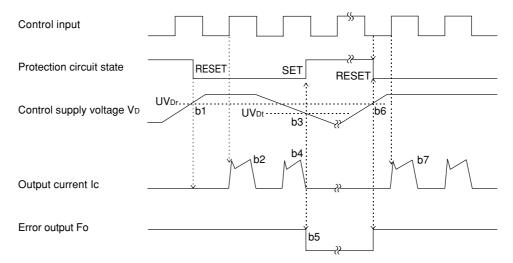
#### [A] Short-Circuit Protection (Lower-arms only with the external shunt resistor and CR filter)

- a1. Normal operation: IGBT ON and carrying current.
- a2. Short circuit detection (SC trigger).
- a3. IGBT gate hard interruption.
- a4. IGBT turns OFF.
- a5. Fo timer starts (tFO(min) =  $20\mu s$ ). a6. Input "L" : IGBT OFF.
- a7. Input "H".
- a8. IGBT OFF in spite of input "H".



#### [B] Under-Voltage Protection (Lower-side, UVD)

- b1. Control supply voltage rising : After the voltage level reaches UVDr, the circuits start to operate when next input is applied. b2. Normal operation : IGBT ON and carrying current.
- b3. Under voltage trip (UVDt).
- b4. IGBT OFF in spite of control input condition.
- b5. Fo output (tF0  $\geq$  20 $\mu$ s and F0 output continuously during UV period).
- b6. Under voltage reset (UVDr).b7. Normal operation: IGBT ON and carrying current.





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#### [C] Under-Voltage Protection (Upper-side, UVDB)

- c1. Control supply voltage rises: After the voltage reaches UVDBr, the circuits start to operate when next input is applied. c2. Normal operation: IGBT ON and carrying current.
- c3. Under voltage trip (UVDBt).
- c4. IGBT OFF in spite of control input signal level, but there is no Fo signal output.
- c5. Under voltage reset (UVDBr).
- c6. Normal operation: IGBT ON and carrying current.

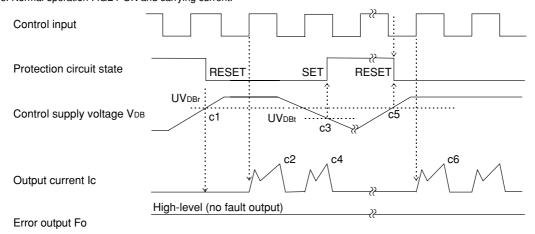
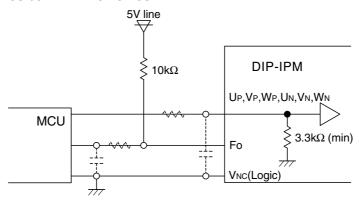


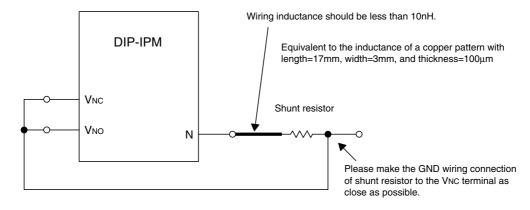
Fig. 8 RECOMMENDED MCU I/O INTERFACE CIRCUIT



Note: The setting of RC coupling at each input (parts shown dotted) depends on the PWM control scheme and the wiring impedance of the printed circuit board.

The DIP-IPM input section integrates a  $3.3k\Omega$  (min) pull-down resistor. Therefore, when using an external filtering resistor, pay attention to the turn-on threshold voltage.

Fig. 9 WIRING CONNECTION OF SHUNT RESISTOR

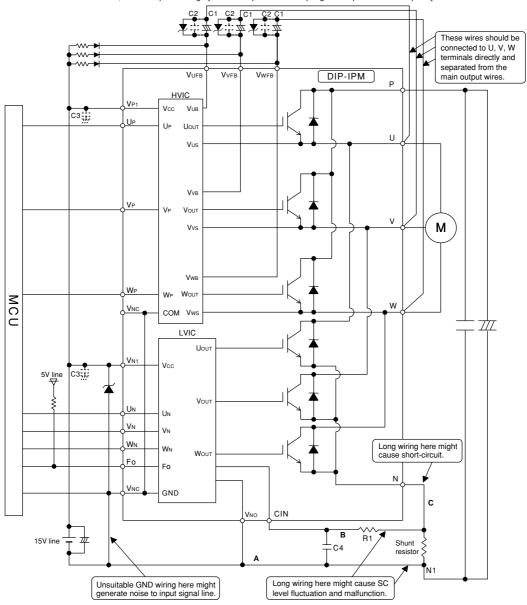




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#### Fig. 10 AN EXAMPLE OF TYPICAL DIP-IPM APPLICATION CIRCUIT

C1: Electrolytic capacitor with super good temperature characteristics C2,C3: 0.22~2µF R-category ceramic capacitors with super good temperature and frequency characteristics



- Note 1 : To prevent malfunction, the wiring of each input should be as short as possible (2~3cm).
  - 2 : By virtue of integrating HVIC inside, direct coupling to MCU without opto-coupler or transformer isolation is possible.

  - 3 : Fo output is open drain type, it should be pulled up to a 5V supply with an approximately 10kΩ resistor.
    4 : The logic of input signal is high-active. The DIP-IPM input signal section integrates a 3.3kΩ (min) pull-down resistor.
  - If using external filtering resistor, ensure the voltage drop of ON signal not below the threshold value.
  - 5 : To prevent malfunction of protection, the wiring of A, B, C should be as short as possible.
  - : Please set the filter R1C4 time constant such that the IGBT can be interrupted within 2µs.
  - : Each capacitor should be located as nearby the pins of the DIP-IPM as possible.
  - :To prevent surge destruction, the wiring between the smoothing capacitor and the P&N1 pins should be as short as possible. Approximately a 0.1~0.22μF snubber capacitor between the P&N1 pins is recommended.
  - : Make external wiring connection between VNO and VNC terminals as shown in Fig.9.
  - 10 : Two VNC terminals (9 & 16 pin) are connected inside DIP-IPM, please connect either one to the 15V power supply GND outside and leave another one open.
  - 11: It is recommended to insert a Zener diode (24V/1W) between each pair of control supply terminals to prevent surge destruction.

